

Amendments to the Specification

Please replace the paragraph beginning at page 6, lines 14-20 with the following rewritten paragraph:

--In the illustrative embodiment, the probe block frame 20 includes a front frame arm 23a, a rear frame arm 23b, a frame base 22, and a frame cover 21. The front frame arm 23a is substantially U-shaped, having two vertical members 25a, 26a separated by a horizontal base 24a. Formed integral to the horizontal base 24a is a frame attachment member 29 configured to mate with an arm attachment base 28 that is attachable to a robotic actuator 12 (~~not shown~~).--

Please replace the paragraph beginning at page 8, lines 1-10 with the following rewritten paragraph:

--During use, the arm attachment base 28 of the probe block frame 20 is fixedly attached to a linear actuator 12 (pneumatic or otherwise, such as an actuating robotic arm, ~~not shown~~) that moves in the probing direction (also referred to as "axis of probing") as indicated by arrow A. The actuator 12 operates to move the frame 20 with independently floating probe blocks 50, 60 therein to engage the probe(s) 52, 53a, 53b, 62 of the respective probe blocks 50, 60 with their respective mating receptacles on the DUT (not shown). When engaged, the alignment features in each independent probe block 50, 60 independently aligns align to the mating features in the DUT and inserts to make electrical contact.--